



Division of Strength of Materials and Structures

Faculty of Power and Aeronautical Engineering



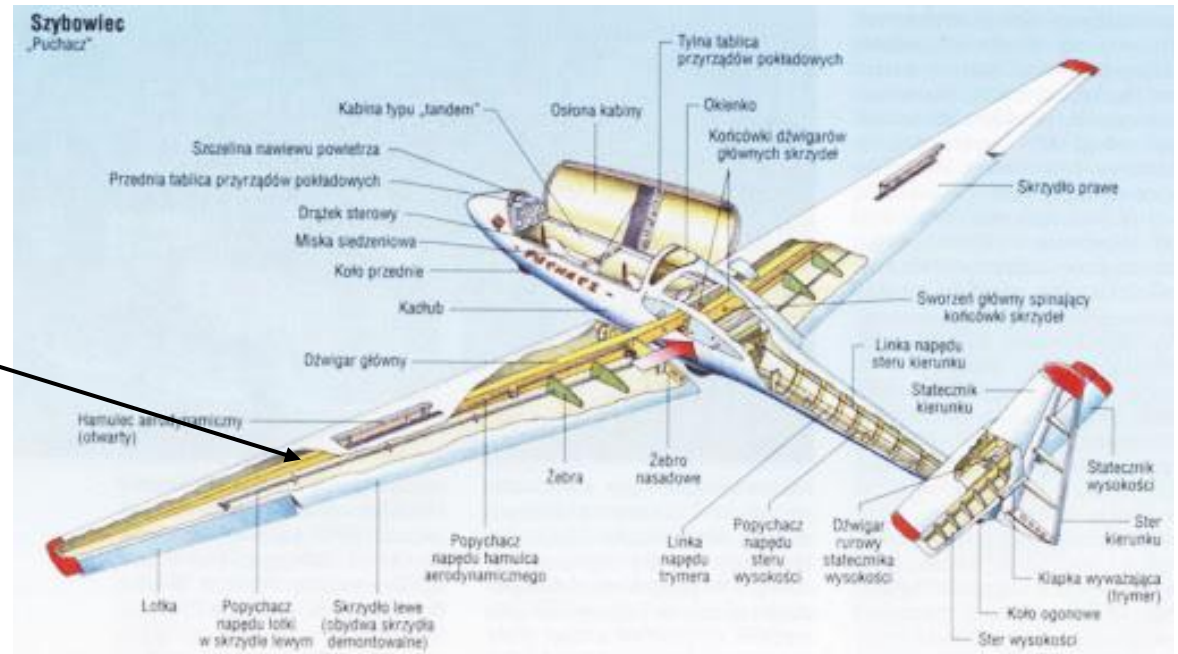
Finite element method (FEM1)

Lecture 9A. 1D beam element

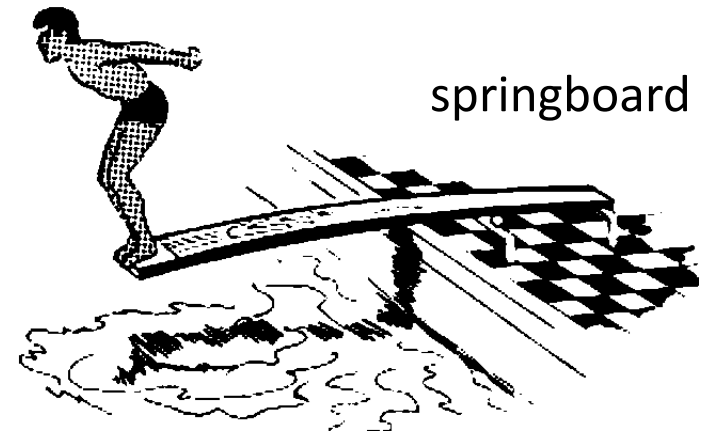
05.2025

Examples of beams

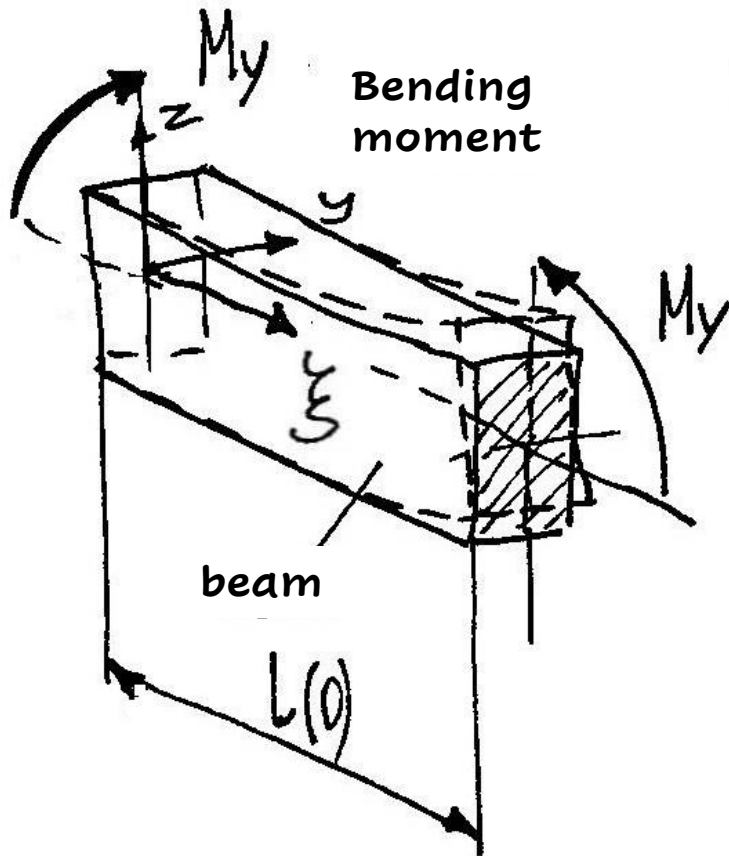
wing spar



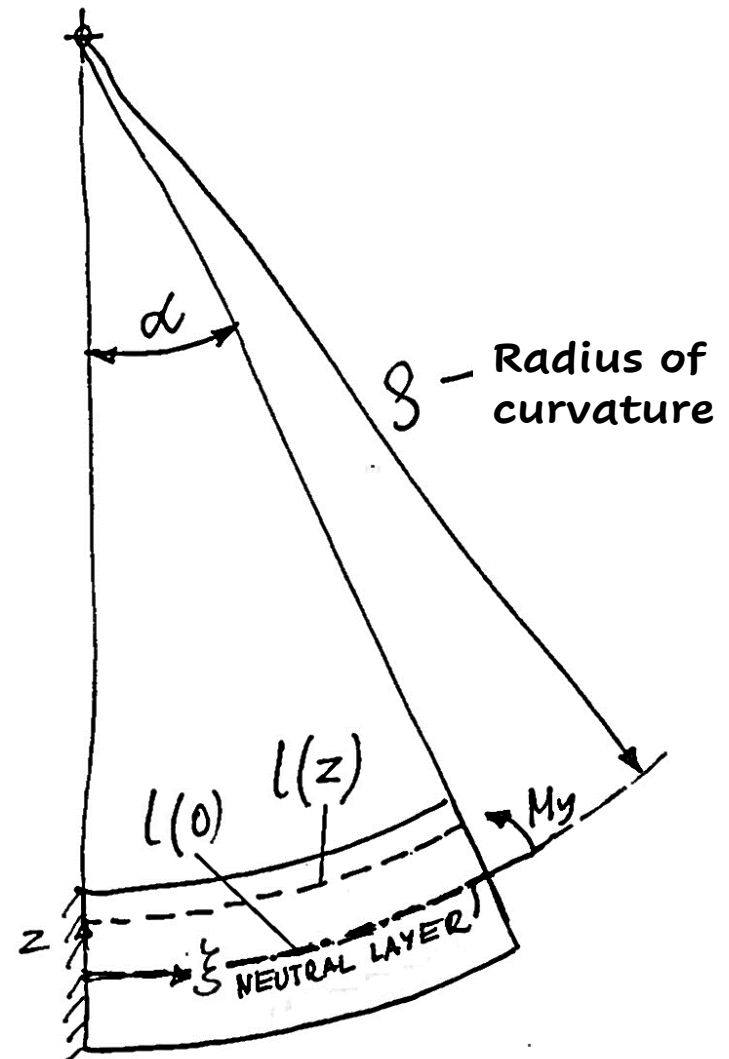
footbridge



Bending without shear force (pure bending)



$$\epsilon_x(z) = \frac{l(z) - l(0)}{l(0)} = \frac{\alpha(\rho - z) - \alpha\rho}{\alpha\rho} = -\frac{z}{\rho}$$

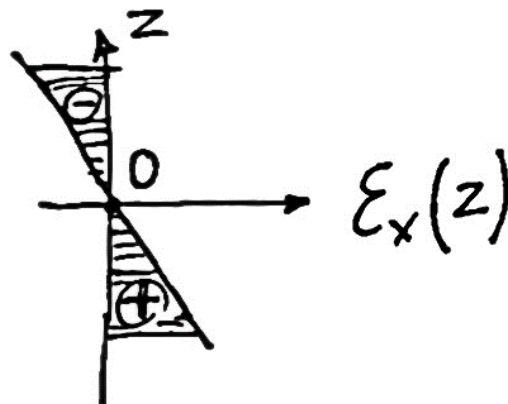


Curvature:

$$\mathcal{K} = \frac{1}{\rho} \approx \frac{d^2 w}{d\xi^2} = w''$$

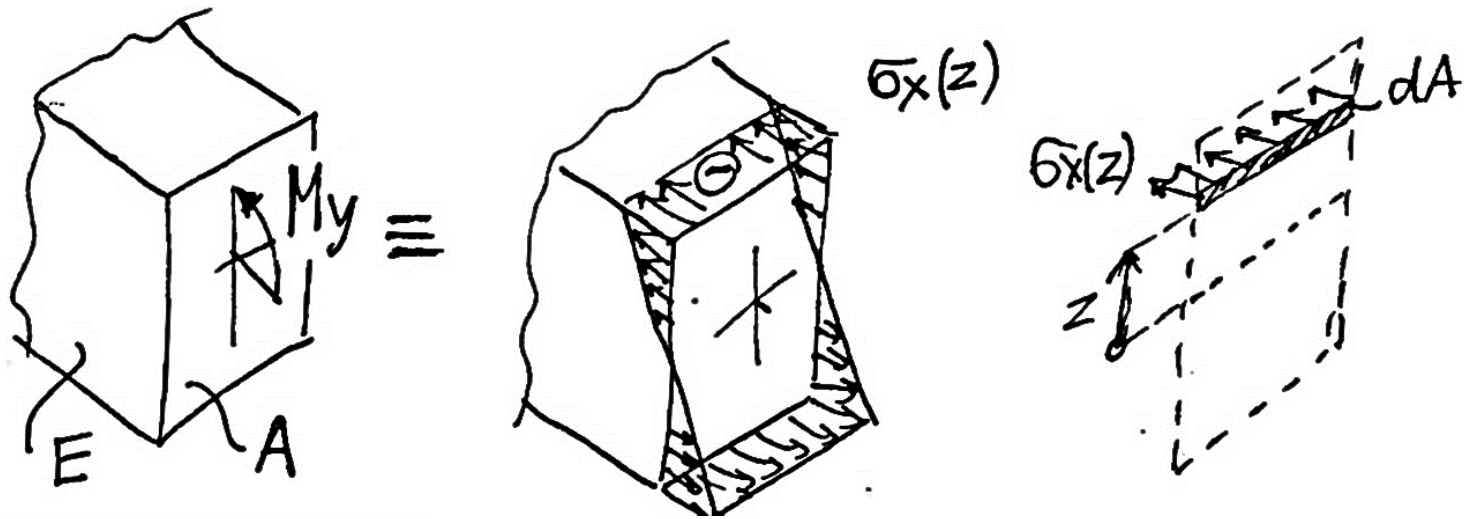
Strain:

$$\epsilon_x(z) = -z \cdot w''$$



Stress:

$$\sigma_x(z) = E \cdot \epsilon_x(z) = -Ez \cdot w''$$



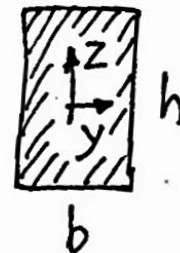
$$M_y = - \int_A \sigma_x(z) \cdot z \, dA = - \int_A -Ez w'' \cdot z \, dA =$$

$$= E w'' \int_A z^2 \, dA \Rightarrow \boxed{M_y = E J_y w''}$$

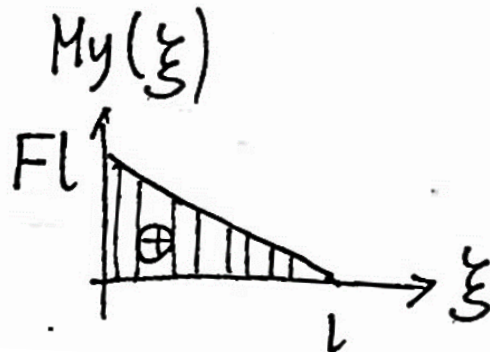
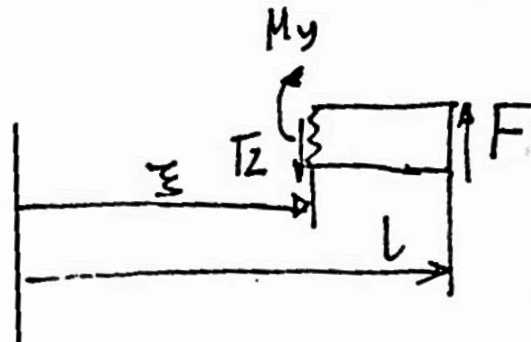
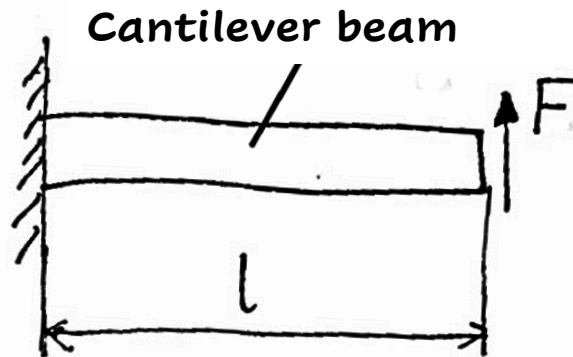
Bending moment in a beam

Second moment of area J_y

$$J_y \doteq \int_A z^2 \, dA = \frac{bh^3}{12} \quad \text{For a rectangle:}$$



Bending with shear force(zginanie poprzeczne)



$$T_z = F$$

$$M_y - F(l - \xi) = 0$$

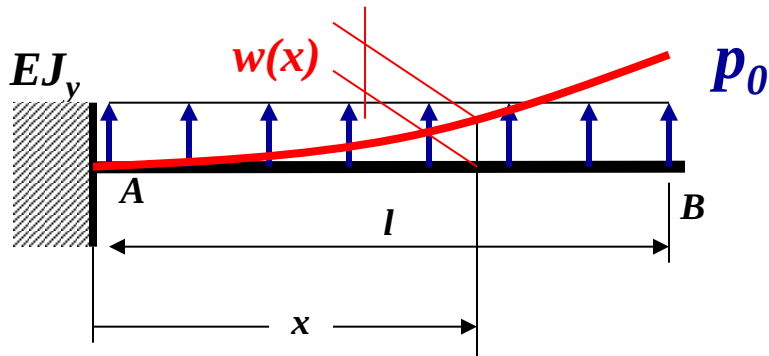
$$M_y = T_z(l - \xi)$$

$$\frac{dM_y}{d\xi} = -T_z$$

Shear force
in a beam

$$T_z = -EJ_y w'''$$

A reminder: cantilever beam - Ritz method solution



Solve a cantilever beam using the Ritz method using a given approximation function:

$$\tilde{w}(x) = a_1 + a_2 \cdot x + a_3 \cdot x^2 + a_4 \cdot x^3$$

Boundary conditions: $\tilde{w}(x=0) = 0$

$$a_1 = 0$$

$\tilde{w}'(x=0) = 0$

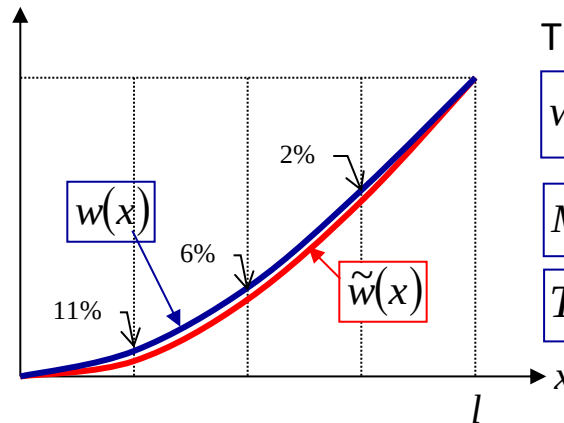
$$a_2 = 0$$

Approximate solution:

$$\tilde{w}(x) = \frac{5}{24} \frac{p_0 l^2}{EJ_y} \cdot x^2 - \frac{1}{12} \frac{p_0 l}{EJ_y} \cdot x^3$$

$$\tilde{M}_g(x) = \frac{5}{12} p_0 l^2 - \frac{1}{2} p_0 l \cdot x$$

$$\tilde{T}(x) = -\frac{1}{2} p_0 l$$

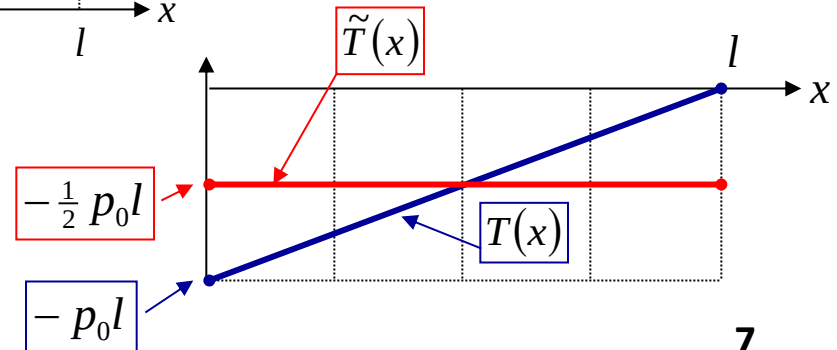
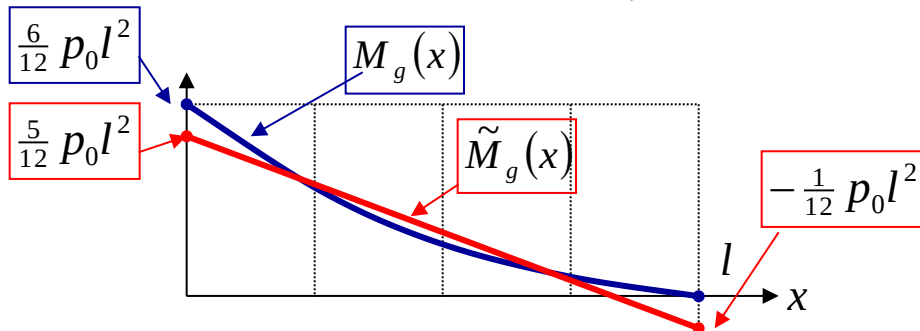


The exact solution:

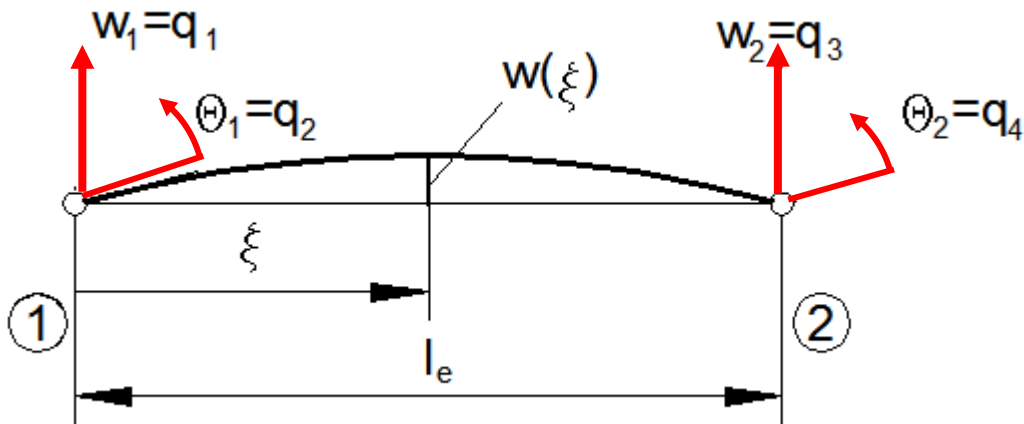
$$w(x) = \frac{6}{24} \frac{p_0 l^2}{EJ_y} \cdot x^2 - \frac{2}{12} \frac{p_0 l}{EJ_y} \cdot x^3 + \frac{1}{24} \frac{p_0}{EJ_y} \cdot x^4$$

$$M_g(x) = \frac{1}{2} p_0 (l - x)^2$$

$$T(x) = -p_0 (l - x)$$



A beam finite element (bending in one plane)



q_1, q_3 – transverse displacements at nodes
 q_2, q_4 – deflection angles at nodes
 (positive signs in counterclockwise direction)

$$n = 2 ; n_p = 2 \rightarrow n_e = n \cdot n_p = 4$$

Let us assume an approximation of the deflection function in the element:

$$w(\xi) = \alpha_1 + \alpha_2 \xi + \alpha_3 \xi^2 + \alpha_4 \xi^3$$

However, new parameters are required: $w_1, w_2, \theta_1, \theta_2$

Vector of nodal parameters:

$$\{q\}_e = \begin{Bmatrix} w_1 \\ \theta_1 \\ w_2 \\ \theta_2 \end{Bmatrix}_e = \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{Bmatrix}_e$$

Nodal approximation:

$$w(\xi) = \sum_{i=1}^4 N_i(\xi) q_i$$

$$w(\xi) = [N(\xi)] \{q\}_e,$$

A beam finite element - the relationship between $\alpha_1, \alpha_2, \alpha_3, \alpha_4$ and q_1, q_2, q_3, q_4

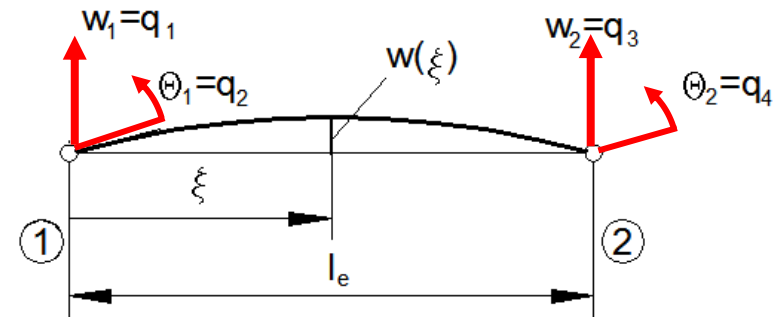
$$w(\xi) = \alpha_1 + \alpha_2 \xi + \alpha_3 \xi^2 + \alpha_4 \xi^3$$

displacement at node 1 $\rightarrow q_1 = w(0) = \alpha_1$,

deflection angle at node 1 $\rightarrow q_2 = \frac{dw}{d\xi}(0) = \alpha_2$,

displacement at node 2 $\rightarrow q_3 = w(l) = \alpha_1 + \alpha_2 l_e + \alpha_3 l_e^2 + \alpha_4 l_e^3$,

deflection angle at node 2 $\rightarrow q_4 = \frac{dw}{d\xi}(l) = \alpha_2 + 2\alpha_3 l_e + 3\alpha_4 l_e^2$.



In matrix notation:

$$\begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{Bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & l_e & l_e^2 & l_e^3 \\ 0 & 1 & 2l_e & 3l_e^2 \end{bmatrix} \begin{Bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \alpha_4 \end{Bmatrix} \rightarrow \begin{Bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \alpha_4 \end{Bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -\frac{3}{l_e^2} & -\frac{2}{l_e} & \frac{3}{l_e^2} & -\frac{1}{l_e} \\ \frac{2}{l_e^3} & \frac{1}{l_e} & -\frac{2}{l_e^3} & \frac{1}{l_e^2} \end{bmatrix} \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{Bmatrix}_e$$

A beam finite element – shape functions

The approximated displacement can be represented in the form:

$$w(\xi) = \begin{bmatrix} 1, \xi, \xi^2, \xi^3 \end{bmatrix} \begin{Bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \alpha_4 \end{Bmatrix} = \begin{bmatrix} N_1(\xi), N_2(\xi), N_3(\xi), N_4(\xi) \end{bmatrix} \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{Bmatrix}$$

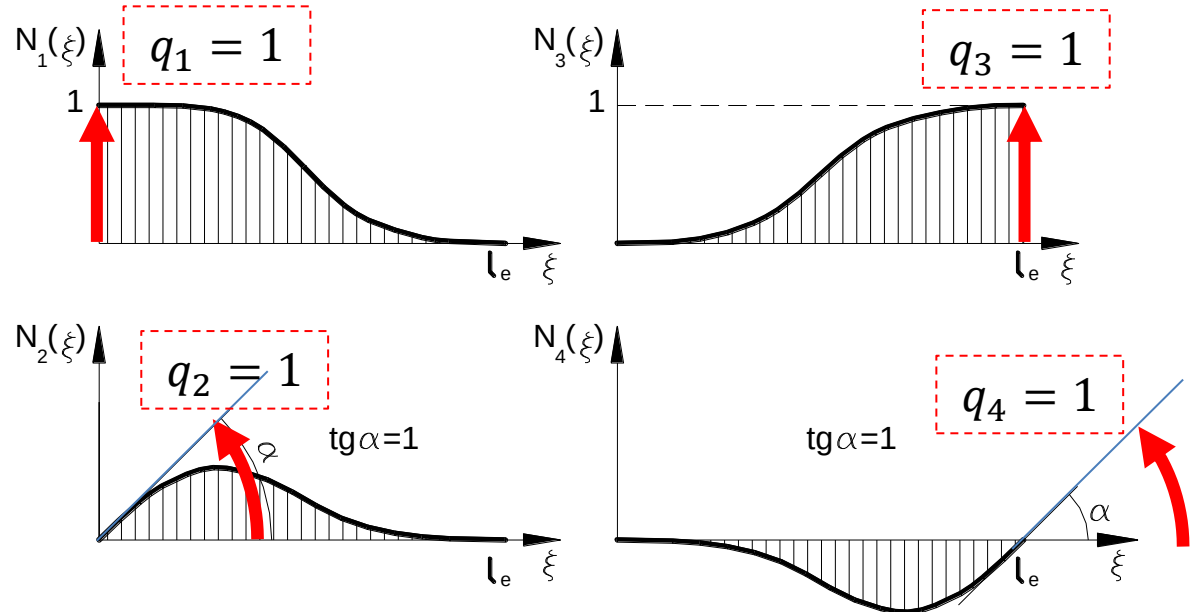
Shape functions of a beam element:

$$N_1(\xi) = 1 - 3\frac{\xi^2}{l_e^2} + 2\frac{\xi^3}{l_e^3},$$

$$N_2(\xi) = \xi - 2\frac{\xi^2}{l_e} + \frac{\xi^3}{l_e^2},$$

$$N_3(\xi) = 3\frac{\xi^2}{l_e^2} - 2\frac{\xi^3}{l_e^3},$$

$$N_4(\xi) = \frac{-\xi^2}{l_e} + \frac{\xi^3}{l_e^2}.$$



A beam finite element - shape functions and their derivatives

$$N' = \frac{dN}{d\xi}, \quad N'' = \frac{d^2 N}{d\xi^2}, \quad N''' = \frac{d^3 N}{d\xi^3}$$

For the first shape function:

$$N_1' = -\frac{6}{l^2} \xi + \frac{6}{l^3} \xi^2, \quad N_1'' = -\frac{6}{l^2} + \frac{12}{l^3} \xi, \quad N_1''' = \frac{12}{l^3}$$

For other shape functions:

$$N_2' = 1 - \frac{4}{l} \xi + \frac{3}{l^2} \xi^2, \quad N_2'' = -\frac{4}{l} + \frac{6}{l^2} \xi, \quad N_2''' = \frac{6}{l^2}$$

$$N_3' = \frac{6}{l^2} \xi - \frac{6}{l^3} \xi^2, \quad N_3'' = \frac{6}{l^2} - \frac{12}{l^3} \xi, \quad N_3''' = -\frac{12}{l^3}$$

$$N_4' = -\frac{2}{l} \xi + \frac{3}{l^2} \xi^2, \quad N_4'' = -\frac{2}{l} + \frac{6}{l^2} \xi, \quad N_4''' = \frac{6}{l^2}$$

A beam finite element – total potential energy

Deflection function and its derivatives:

$$\begin{aligned} w(\xi) &= [N(\xi)] \{q\}_e, \\ w'(\xi) &= [N'(\xi)] \{q\}_e, \\ w''(\xi) &= [N''(\xi)] \{q\}_e. \end{aligned}$$

Total potential energy of a beam of length l_e :

$$V_e = U_e - W_{ze} = \frac{EI}{2} \int_0^{l_e} (w''(\xi))^2 d\xi - \int_0^{l_e} p(\xi) w(\xi) d\xi - \sum_i P_i w_i - \sum_j M_j \vartheta_j$$

$$\begin{aligned} U_e &= \frac{EI}{2} \int_0^{l_e} w''(\xi) w''(\xi) d\xi = \frac{EI}{2} \int_0^{l_e} [q]_e \{N''\} [N'']^T \{q\}_e d\xi = \\ &= \frac{EI}{2} [q]_e \int_0^{l_e} \begin{bmatrix} N_1'' N_1'' & N_1'' N_2'' & N_1'' N_3'' & N_1'' N_4'' \\ N_2'' N_1'' & N_2'' N_2'' & N_2'' N_3'' & N_2'' N_4'' \\ N_3'' N_1'' & N_3'' N_2'' & N_3'' N_3'' & N_3'' N_4'' \\ N_4'' N_1'' & N_4'' N_2'' & N_4'' N_3'' & N_4'' N_4'' \end{bmatrix} d\xi \{q\}_e. \end{aligned}$$

A beam finite element – macierz sztywności

Elastic strain energy of the beam:

$$U_e = \frac{1}{2} [q]_e [k]_e \{q\}_e$$
$$[k]_e = EI \begin{bmatrix} \int_0^{l_e} N_1'' N_1'' d\xi & \int_0^{l_e} N_1'' N_2'' d\xi & \int_0^{l_e} N_1'' N_3'' d\xi & \int_0^{l_e} N_1'' N_4'' d\xi \\ \int_0^{l_e} N_2'' N_1'' d\xi & \int_0^{l_e} N_2'' N_2'' d\xi & \int_0^{l_e} N_2'' N_3'' d\xi & \int_0^{l_e} N_2'' N_4'' d\xi \\ \int_0^{l_e} N_3'' N_1'' d\xi & \int_0^{l_e} N_3'' N_2'' d\xi & \int_0^{l_e} N_3'' N_3'' d\xi & \int_0^{l_e} N_3'' N_4'' d\xi \\ \int_0^{l_e} N_4'' N_1'' d\xi & \int_0^{l_e} N_4'' N_2'' d\xi & \int_0^{l_e} N_4'' N_3'' d\xi & \int_0^{l_e} N_4'' N_4'' d\xi \end{bmatrix}$$

Stiffness matrix of a beam element:

$$[k]_e = \frac{2EI}{l_e^3} \begin{bmatrix} 6 & 3l_e & -6 & 3l_e \\ 3l_e & 2l_e^2 & -3l_e & l_e^2 \\ -6 & -3l_e & 6 & -3l_e \\ 3l_e & l_e^2 & -3l_e & 2l_e^2 \end{bmatrix}$$

A beam finite element – equivalent forces

Work of external load:
$$W_{ze}^p = \int_0^{l_e} p(\xi) w(\xi) d\xi = \int_0^{l_e} p(\xi) [N(\xi)] \{q\}_e d\xi$$

$$= \int_0^{l_e} [N_1(\xi)p(\xi), N_2(\xi)p(\xi), N_3(\xi)p(\xi), N_4(\xi)p(\xi)] \{q\}_e d\xi,$$

$$W_{ze}^p = [F_1^e, F_2^e, F_3^e, F_4^e]_e \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{Bmatrix} = [F]_e \{q\}_e$$

Nodal equivalent forces resulting from continuous load output:

$$F_i^e = \int_0^{l_e} N_i(\xi) p(\xi) d\xi$$

Example: equivalent forces resulting from a constant continuous load

Nodal forces resulting from continuous output:
$$F_i^e = \int_0^{l_e} N_i(\xi) p(\xi) d\xi$$

For constant continuous load:

$$F_1^e = \int_0^{l_e} N_1(\xi) \cdot p_0 \cdot d\xi = \int_0^{l_e} \left(1 - \frac{3}{l_e^2} \xi^2 + \frac{2}{l_e^3} \xi^3\right) p_0 \cdot d\xi = \frac{p_0 l_e}{2}$$

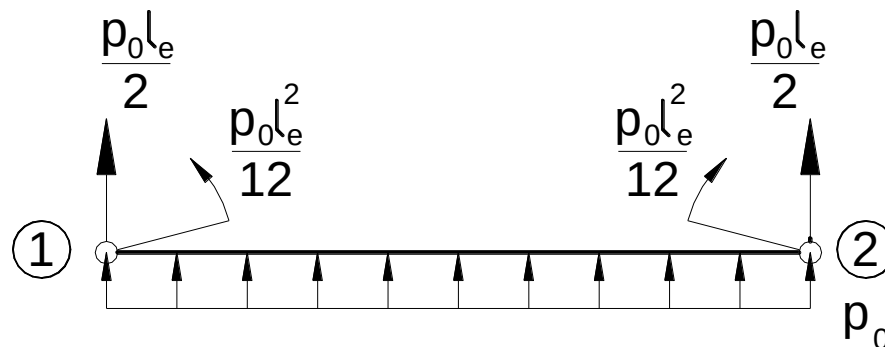
$$F_2^e = \int_0^{l_e} N_2(\xi) \cdot p_0 \cdot d\xi = \int_0^{l_e} \left(\xi - \frac{2}{l_e} \xi^2 + \frac{1}{l_e^2} \xi^3\right) p_0 \cdot d\xi = \frac{p_0 l_e^2}{12}$$

e.t.c.

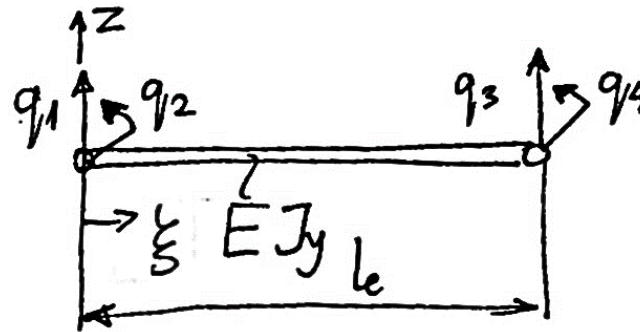
$$F_1^e = F_3^e = \frac{p_0 l_e}{2}$$

$$F_2^e = \frac{p_0 l_e^2}{12}$$

$$F_4^e = \frac{-p_0 l_e^2}{12}$$



A beam finite element – list of search functions



$$\{q\}_e = [q_1, q_2, q_3, q_4]_{1 \times 4}$$

Deflection: $w(\xi) = \underset{1 \times 4}{[N]} \cdot \underset{4 \times 1}{\{q\}_e}$ – Polynomial of the 3rd order

Bending moment: $M_y(\xi) = EJ_y w'' = EJ_y \underset{1 \times 4}{[N'']} \cdot \underset{4 \times 1}{\{q\}_e}$ – Linear function

Shear force: $T_z(\xi) = -EJ_y w''' = -EJ_y \underset{1 \times 4}{[N''']} \cdot \underset{4 \times 1}{\{q\}_e}$ – Constant value

DOF
Solution

$$\{q\}_{N \times 1} = [K]_{N \times N}^{-1} \cdot \{F\}_{N \times 1}$$

Element
solution

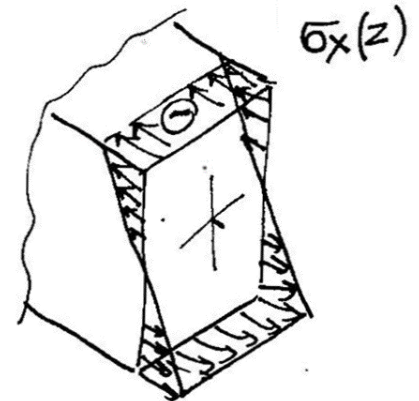
$$M_y(\xi) = E J_y \left[N''(\xi) \right]_{1 \times 4} \cdot \{q\}_{4 \times 1} e, \quad T_z(\xi) = -E J_y \left[N'''(\xi) \right]_{1 \times 4} \cdot \{q\}_{4 \times 1} e$$

$$\sigma_x(\xi, z) = -M_y(\xi) \cdot \frac{z}{J_y} = -E \left[N''(\xi) \right]_{1 \times 4} \cdot \{q\}_{4 \times 1} e \cdot z$$

$$\tau_{xz}(\xi, z) = f(z) \cdot T_z(\xi) \frac{\text{rectangle}}{b \times h} \frac{3}{2} \left(1 - \left(\frac{2z}{h} \right)^2 \right) / b h \cdot T_z(\xi)$$

$$\epsilon_x(\xi, z) = \sigma_x(\xi, z) / E = - \left[N''(\xi) \right]_{1 \times 4} \cdot \{q\}_{4 \times 1} e \cdot z$$

$$w(\xi) = \left[N(\xi) \right]_{1 \times 4} \cdot \{q\}_{4 \times 1} e$$



A beam finite element – system of equations

Total potential energy of the beam element:

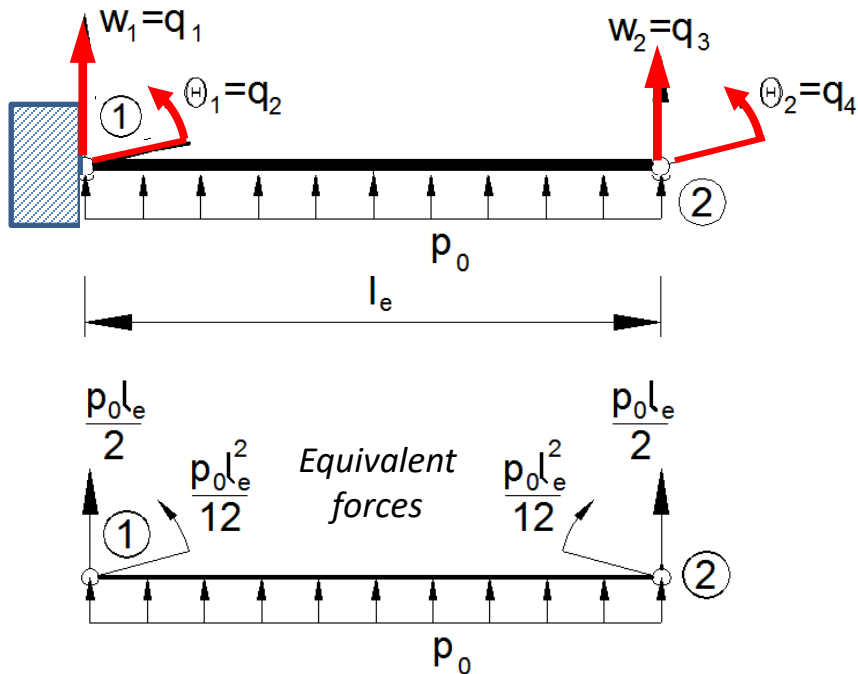
$$V_e = U_e - W_{ze} = \frac{1}{2} \underbrace{\begin{bmatrix} q \end{bmatrix}_e}_{1 \times 4} \underbrace{\begin{bmatrix} k \end{bmatrix}_e}_{4 \times 4} \underbrace{\{q\}_e}_{4 \times 1} - \underbrace{\begin{bmatrix} q \end{bmatrix}_e}_{1 \times 4} \underbrace{\{F\}_e}_{4 \times 1}$$

Condition for minimizing total potential energy:

$$\frac{\partial V_e}{\partial q_i} = 0 \quad i = 1, 2, 3, \dots, n$$

$$\boxed{\begin{bmatrix} k \end{bmatrix}_e \{q\}_e = \{F\}_e} \quad \Rightarrow \quad \frac{2EI}{l_e^3} \begin{bmatrix} 6 & 3l_e & -6 & 3l_e \\ 3l_e & 2l_e^2 & -3l_e & l_e^2 \\ -6 & -3l_e & 6 & -3l_e \\ 3l_e & l_e^2 & -3l_e & 2l_e^2 \end{bmatrix} \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{Bmatrix}_e = \begin{Bmatrix} F_1 \\ F_2 \\ F_3 \\ F_4 \end{Bmatrix}_e$$

Example: cantilever beam loaded with a uniformly distributed transverse load (*one element*)



Vector of nodal parameters:

$$\{q\}_e = \begin{Bmatrix} w_1 \\ \theta_1 \\ w_2 \\ \theta_2 \end{Bmatrix}_e = \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{Bmatrix}_e = \begin{Bmatrix} 0 \\ 0 \\ q_3 \\ q_4 \end{Bmatrix}_e$$

$$\frac{2EI}{l^3} \begin{bmatrix} 6 & 3l & 6 & 3l \\ 3l & 2l^2 & 3l & l^2 \\ -6 & -3l & 6 & -3l \\ 3l & l^2 & -3l & 2l^2 \end{bmatrix} \begin{Bmatrix} 0 \\ 0 \\ q_3 \\ q_4 \end{Bmatrix} = \begin{Bmatrix} F_1 \\ F_2 \\ \frac{p_0 l}{2} \\ -\frac{p_0 l^2}{12} \end{Bmatrix}$$

$$\begin{aligned} \frac{2EI}{l^3} (6q_3 - 3lq_4) &= \frac{p_0 l}{2}, \\ \frac{2EI}{l^3} (-3lq_3 + 2l^2 q_4) &= -\frac{p_0 l^2}{12}, \end{aligned}$$



$$q_3 = \frac{1}{8} \frac{p_0 l^4}{EI}$$

$$q_4 = \frac{1}{6} \frac{p_0 l^3}{EI}$$

$$w(\xi) = \sum_{i=1}^4 N_i(\xi) q_i$$



$$w(\xi) = \left(\frac{3}{8} - \frac{1}{6} \right) \frac{p_0 l^2}{EI} \xi^2 + \left(\frac{-2}{8} + \frac{1}{6} \right) \frac{p_0 l}{EI} \xi^3 = \frac{5}{24} \frac{p_0 l^2}{EI} \xi^2 - \frac{p_0 l}{12EI} \xi^3$$

Example: cantilever beam loaded with a uniformly distributed transverse load (*one element*)

Reactions:

$$\frac{2EI}{l^3} \begin{bmatrix} 6 & 3l & -6 & 3l \\ 3l & 2l^2 & 3l & l^2 \\ -6 & -3l & 6 & -3l \\ 3l & l^2 & -3l & 2l^2 \end{bmatrix} \begin{Bmatrix} q_3 \\ q_4 \end{Bmatrix} = \begin{Bmatrix} F_1 \\ F_2 \\ \frac{p_0 l}{2} \\ -\frac{p_0 l^2}{12} \end{Bmatrix}$$

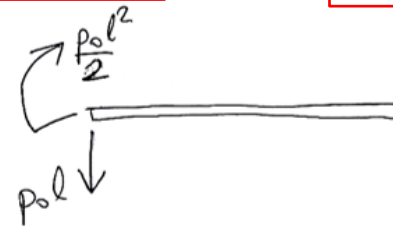
$$q_3 = \frac{1}{8} \frac{p_0 l^4}{EI}$$

$$q_4 = \frac{1}{6} \frac{p_0 l^3}{EI}$$

$$\begin{cases} \frac{2EI}{l^3} (-6 \cdot q_3 + 3l \cdot q_4) = R_1 + \frac{p_0 l}{2} \\ \frac{2EI}{l^3} (-3l \cdot q_3 + l^2 \cdot q_4) = R_2 + \frac{p_0 l^2}{12} \end{cases}$$

$$R_1 = -p_0 l$$

$$R_2 = -\frac{p_0 l^2}{2}$$

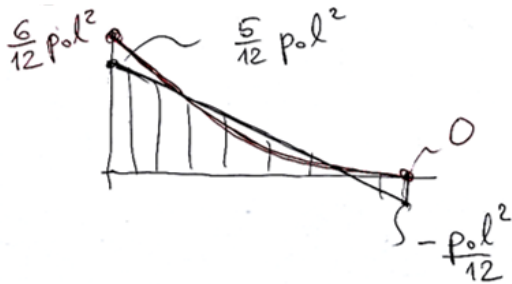


Bending moment:

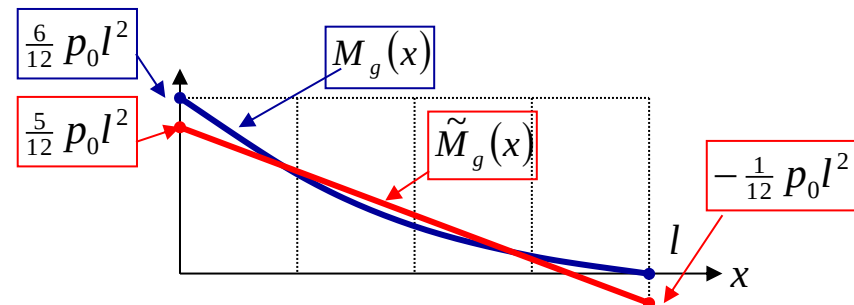
$$M_g = EJ \cdot w''(\xi) = EJ \cdot \sum_i N_i''(\xi) \cdot q_i$$

$$M_g = EJ (N_3''(\xi) \cdot q_3 + N_4''(\xi) \cdot q_4)$$

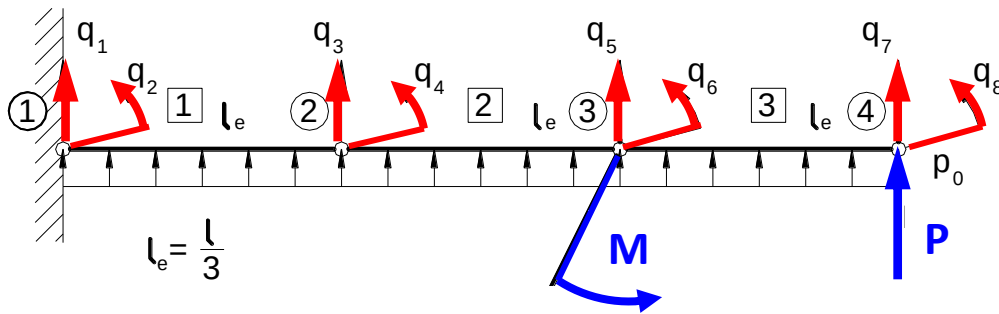
$$M_g = \frac{5}{12} p_0 l^2 - \frac{p_0 l}{2} \cdot \xi$$



As in the Ritz solution!



Example: cantilever beam loaded with a uniformly distributed transverse load, nodal loads
(*three elements*)



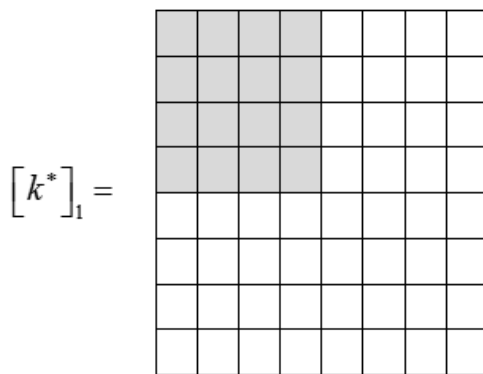
Vector of nodal parameters:

$$\{q\} = \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \\ q_5 \\ q_6 \\ q_7 \\ q_8 \end{Bmatrix} = \begin{Bmatrix} w_1 \\ \theta_1 \\ w_2 \\ \theta_2 \\ w_3 \\ \theta_3 \\ w_4 \\ \theta_4 \end{Bmatrix}$$

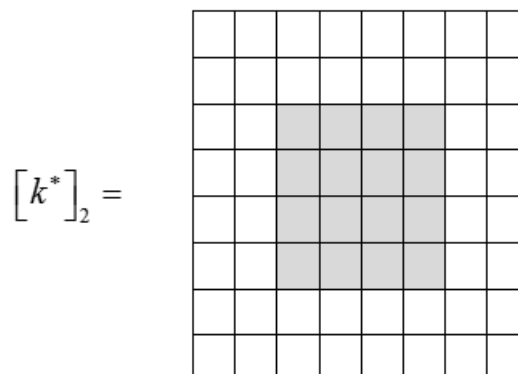
Elastic strain energy in every element:

$$U_e = \frac{1}{2} [q]_e [k]_e \{q\}_e = \frac{1}{2} [q]_{1 \times N} [k^*]_{N \times N} \{q\}_{N \times 1}$$

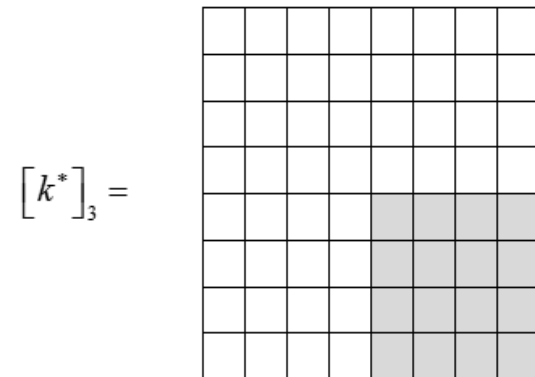
Extended Element Stiffness Matrices:



q_1, q_2, q_3, q_4



q_3, q_4, q_5, q_6



q_5, q_6, q_7, q_8

Example: cantilever beam loaded with a uniformly distributed transverse load, nodal loads
(*three elements*)

Elastic strain energy of the entire beam:

$$U = \sum_{e=1}^{LE} U_e = \frac{1}{2} [q] \left(\sum_{i=1}^{LE} [k^*]_e \right) \{q\} = \frac{1}{2} [q] [K] \{q\}$$

Total potential energy of the system:

$$V = U - W_z = \frac{1}{2} [q] [K] \{q\} - [q] \{F\}$$

The condition of minimum total potential energy of the system:

$$\frac{\partial V}{\partial q_i} = 0 \quad i = 1, 2, 3, \dots, n$$

$$[K] \{q\} = \{F\} \quad + \text{displacement boundary conditions}$$

$$M_q(\xi) = EI w''(\xi) = EI \begin{bmatrix} N_1'' & N_2'' & N_3'' & N_4'' \end{bmatrix} \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{Bmatrix}_e, \quad M_q(\xi) = \left[\frac{12}{l_e^3} \left(\xi - \frac{l_e}{2} \right) q_1 + \frac{6}{l_e^2} \left(\xi - \frac{2}{3} l_e \right) q_2 - \frac{12}{l_e^3} \left(\xi - \frac{l_e}{2} \right) q_3 + \frac{6}{l_e^2} \left(\xi - \frac{l_e}{3} \right) q_4 \right] EI,$$

$$T(\xi) = -EI w'''(\xi) = EI \begin{bmatrix} N_1''' & N_2''' & N_3''' & N_4''' \end{bmatrix} \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{Bmatrix}_e. \quad T(\xi) = - \left[\frac{12}{l_e^3} (q_1 - q_3) + \frac{6}{l_e^2} (q_2 + q_4) \right] EI.$$

Example: cantilever beam loaded with a uniformly distributed transverse load, nodal loads
(three elements)

k_{11}^1	k_{12}^1	k_{13}^1	k_{14}^1	0	0	0	0
k_{21}^1	k_{22}^1	k_{23}^1	k_{24}^1	0	0	0	0
k_{31}^1	k_{32}^1	$k_{33}^1 + k_{11}^2$	$k_{34}^1 + k_{12}^2$	k_{13}^2	k_{14}^2	0	0
k_{41}^1	k_{42}^1	$k_{43}^1 + k_{21}^2$	$k_{44}^1 + k_{22}^2$	k_{23}^2	k_{24}^2	0	0
0	0	k_{31}^2	k_{32}^2	$k_{33}^2 + k_{11}^3$	$k_{34}^2 + k_{12}^3$	k_{13}^3	k_{14}^3
0	0	k_{41}^2	k_{42}^2	$k_{43}^2 + k_{21}^3$	$k_{44}^2 + k_{22}^3$	k_{23}^3	k_{24}^3
0	0	0	0	k_{31}^3	k_{32}^3	k_{33}^3	k_{34}^3
0	0	0	0	k_{41}^3	k_{42}^3	k_{43}^3	k_{44}^3

$$\begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \\ q_5 \\ q_6 \\ q_7 \\ q_8 \end{Bmatrix} = \begin{Bmatrix} F_1 \\ F_2 \\ F_3 \\ F_4 \\ F_5 \\ F_6 \\ F_7 \\ F_8 \end{Bmatrix}$$

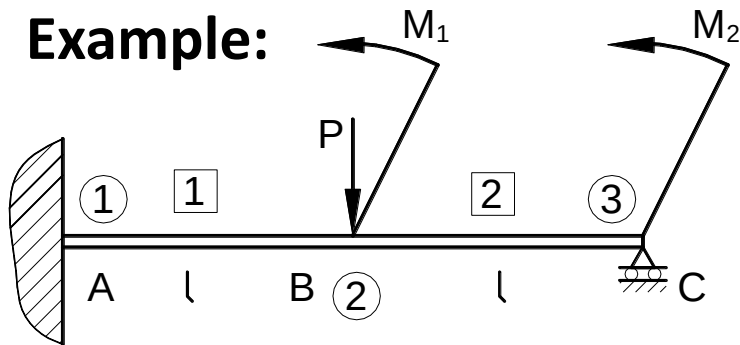
6	$3l_e$	-6	$3l_e$	0	0	0	0
$3l_e$	$2l_e^2$	$-3l_e$	l_e^2	0	0	0	0
-6	$-3l_e$	12	0	-6	$3l_e$	0	0
$3l_e$	l_e^2	0	$4l_e^2$	$-3l_e$	l_e^2	0	0
0	0	-6	$-3l_e$	12	0	-6	$3l_e$
0	0	$3l_e$	l_e^2	0	$4l_e^2$	$-3l_e$	l_e^2
0	0	0	0	-6	$-3l_e$	6	$-3l_e$
0	0	0	0	$3l_e$	l_e^2	$-3l_e$	$2l_e^2$

$$\frac{2EI}{l_e^3} \begin{Bmatrix} 0 \\ 0 \\ q_3 \\ q_4 \\ q_5 \\ q_6 \\ q_7 \\ q_8 \end{Bmatrix} = \begin{Bmatrix} F_1 \\ F_2 \\ p_0 l_e \\ 0 \\ p_0 l_e \\ M \\ P + \frac{p_0 l_e}{2} \\ \frac{-p_0 l_e^2}{12} \end{Bmatrix}$$

Typical FEM calculations

1. Determination of the stiffness matrix of the elements $[k]_e$
2. Aggregation of the matrix of elements into the global matrix $[K]$
3. Determination of the equivalent load vector $\{F\}$
4. Introduction of boundary conditions – determination of all the searched parameters $\{q\}$
5. Determination of internal forces (moments and shear forces) and normal and shear stresses

Example:



$$[K] = \frac{2EI}{l^3}$$

6	3l	-6	3l		
3l	2l ²	-3l	l ²		
-6	-3l	6+6	-3l+3l	-6	3l
3l	l ²	-3l+3l	2l ² +2l ²	-3l	l ²
		-6	-3l	6	-3l
		3l	l ²	-3l	2l ²

$$\{q\} = \begin{Bmatrix} w_1 \\ \theta_1 \\ w_2 \\ \theta_2 \\ w_3 \\ \theta_3 \end{Bmatrix} = \begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \\ q_5 \\ q_6 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \\ q_3 \\ q_4 \\ 0 \\ q_6 \end{Bmatrix}$$

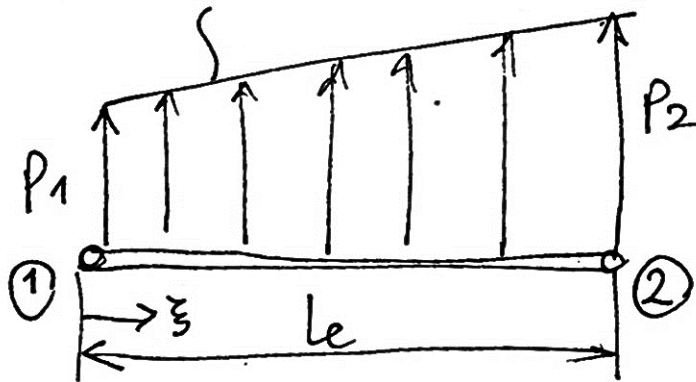
$$\{F\} = \begin{Bmatrix} F_1 \\ F_2 \\ -P \\ M_1 \\ F_5 \\ M_2 \end{Bmatrix}$$

$$\frac{2EI}{l^3} \begin{bmatrix} 12 & 0 & 3l \\ 0 & 4l^2 & l^2 \\ 3l & l^2 & 2l^2 \end{bmatrix} \begin{Bmatrix} q_3 \\ q_4 \\ q_6 \end{Bmatrix} = \begin{Bmatrix} -P \\ M_1 \\ M_2 \end{Bmatrix}$$

$$\begin{Bmatrix} q_3 \\ q_4 \\ q_6 \end{Bmatrix} = \begin{Bmatrix} w_2 \\ \theta_2 \\ \theta_3 \end{Bmatrix} = \frac{l}{96EI} \begin{bmatrix} 7l^2 & 3l & -12l \\ 3l & 15 & -12 \\ -12l & -12 & 48 \end{bmatrix} \begin{Bmatrix} -P \\ M_1 \\ M_2 \end{Bmatrix}$$

Example: find the components of the equivalent load for a linearly distributed transverse load

$$p(\xi) = \frac{p_2 - p_1}{l_e} \cdot \xi + p_1$$



$$\{F\}_e = \{F_{1e}, F_{2e}, F_{3e}, F_{4e}\}_e$$

1) Transverse equivalent force at node 1:

$$\begin{aligned} F_{1e} &= \int_0^{l_e} p(\xi) \cdot N_1(\xi) d\xi = \int_0^{l_e} \left(\frac{p_2 - p_1}{l_e} \cdot \xi + p_1 \right) \left(1 - \frac{3}{2l_e} \xi^2 + \frac{2}{l_e^3} \xi^3 \right) d\xi = \\ &= \frac{p_1 l_e}{2} + \frac{3}{20} (p_2 - p_1) \cdot l_e \end{aligned}$$

2) Equivalent moment at node 1:

$$\begin{aligned} F_{2e} &= \int_0^l p(\xi) \cdot N_2(\xi) d\xi = \int_0^l \left(\frac{p_2 - p_1}{l} \cdot \xi + p_1 \right) \left(\xi - \frac{2}{l} \xi^2 + \frac{1}{l^2} \xi^3 \right) d\xi = \\ &= \frac{p_1 l^2}{12} + \frac{1}{30} (p_2 - p_1) l^2 \end{aligned}$$

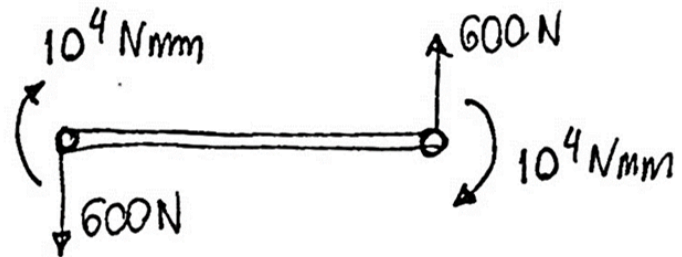
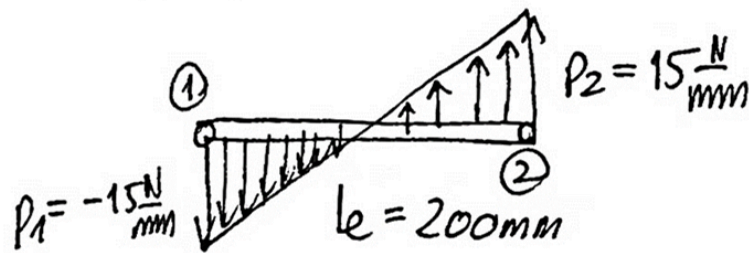
3) Transverse equivalent force at node 2:

$$\begin{aligned} F_{3e} &= \int_0^l p(\xi) N_3(\xi) d\xi = \int_0^l \left(\frac{p_2 - p_1}{l} \cdot \xi + p_1 \right) \left(\frac{3}{l^2} \xi^2 - \frac{2}{l^3} \xi^3 \right) d\xi = \\ &= \frac{p_1 l}{2} + \frac{7}{20} (p_2 - p_1) l \end{aligned}$$

4) Equivalent moment at node 2:

$$\begin{aligned} F_{4e} &= \int_0^l p(\xi) \cdot N_4(\xi) d\xi = \int_0^l \left(\frac{p_2 - p_1}{l} \cdot \xi + p_1 \right) \left(-\frac{1}{l} \xi^2 + \frac{1}{l^2} \xi^3 \right) d\xi = \\ &= -\frac{p_1 l^2}{12} - \frac{(p_2 - p_1) l^2}{20} \end{aligned}$$

Example: find the components of the equivalent load for a linearly distributed transverse load



$$F_{1e} = \frac{-15 \frac{\text{N}}{\text{mm}} \cdot 200 \text{ mm}}{2} + \frac{3}{20} \left(15 \frac{\text{N}}{\text{mm}} - (-15 \frac{\text{N}}{\text{mm}}) \right) \cdot 200 \text{ mm} = -600 \text{ N}$$

$$F_{2e} = \frac{-15 \frac{\text{N}}{\text{mm}} \cdot 200^2 \text{ mm}^2}{12} + \frac{1}{30} \left(30 \frac{\text{N}}{\text{mm}} \right) \cdot 200^2 \text{ mm}^2 = -10^4 \text{ Nmm}$$

$$F_{3e} = \frac{-15 \frac{\text{N}}{\text{mm}} \cdot 200 \text{ mm}}{2} + \frac{7}{20} \left(30 \frac{\text{N}}{\text{mm}} \right) \cdot 200 \text{ mm} = 600 \text{ N}$$

$$F_{4e} = - \frac{(-15 \frac{\text{N}}{\text{mm}}) \cdot 200^2 \text{ mm}^2}{12} - \frac{(30 \frac{\text{N}}{\text{mm}})}{20} \cdot 200^2 \text{ mm}^2 = -10^4 \text{ Nmm}$$